



*Interactive Retrieval and
Mining of Visual Content*

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1



Outline


- Why interactive retrieval and mining?
- Active semi-supervised clustering
- Relevance feedback with global or local features
- Scalability issues for relevance feedback
- Scalable video mining by copy detection
- Interactive retrieval after prior mining
- Information retrieval beyond ranking



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2



Why interactive retrieval/mining

- Define/find task-dependent or user-dependent complex visual concepts/patterns
- Available information
 1. Data-issued similarities (visual, spatial relations...)
 - Inherent to the data!
 2. User-provided valuable information
 - Class labels, pairwise constraints, ...
 - Typically approximate and/or uncertain
 - Typically scarce and expensive

→ Combine these information sources!



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Active semi-supervised clustering

- Supervision (information regarding the target: class labels, constraints, ...) is only available for (a small) part of the data, while data-issued similarities are available for all the data

→ semi-supervised learning
- High cost of
 - ◆ Acquiring supervision (requires interaction with the user)
 - ◆ Using the data (algorithmic complexity)

→ active learning: the algorithm selects the data for which supervision information is required from the user

→ Maximal performance improvement at minimal cost



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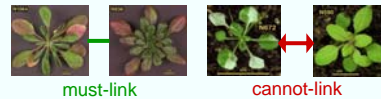
Case: similarities + constraints

■ Application context (image database categorization)

- ◆ Large unknown (or little known) database
- ◆ Direct clustering has poor performance
 - Supervision is needed
- ◆ Image classes are unknown *a priori*
 - Users cannot provide class label but can say whether 2 images should be in a same class (*must-link* constraint) or in different classes (*cannot-link* constraint)
 - Given the size of the database, the amount of supervision should be minimal



© <http://arabidopsis.info>



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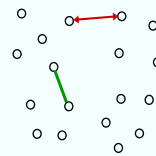
5

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Active clustering with constraints

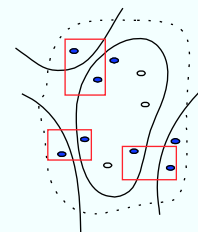
■ Semi-supervised aspect

- ◆ Combine two sources of information:
 1. Similarities between image descriptors
 2. Pairwise constraints
- New objective function (based on CA)



■ Active aspect

- ◆ Minimize number of needed constraints ← maximize information transfer user → system
- 2 complementary selection criteria:
 1. **Informative** constraints: ambiguous images from the least well defined clusters
 2. **Low redundancy** between the constraints



[GCB08]



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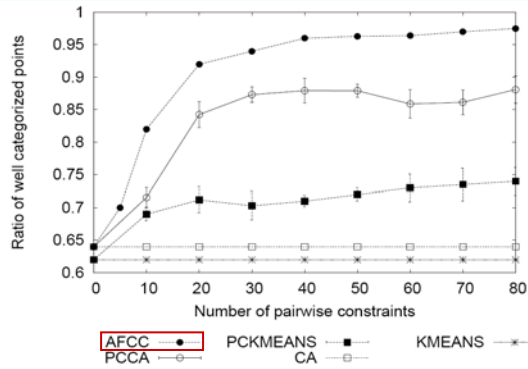
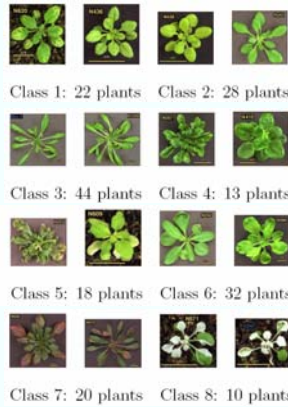
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Illustrative results

Arabidopsis thaliana database



[GCB08]

Images provided by NASC (<http://arabidopsis.info>), ground truth by INRA (<http://www.inra.fr>)



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7

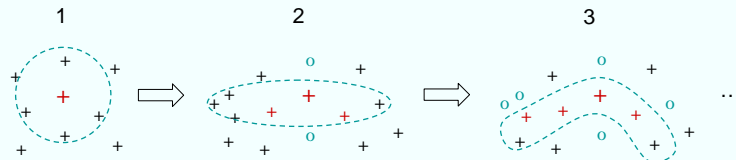


Retrieval with relevance feedback

1. Query by example



2. Iterative interactive retrieval with relevance feedback



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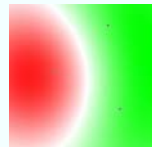
8



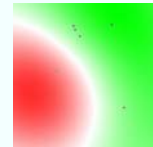
Active learning for RF

- System must select unlabeled sample so as to maximize the transfer of information from the user to the system

→ Ambiguousness

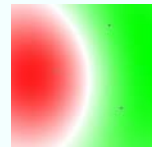


Before selection

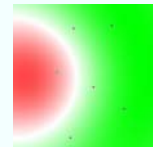


After selection, feedback, estimation

→ Low redundancy



Before selection



After selection, feedback, estimation

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9



Illustrative example 1

Goal: find portraits

Base of 7500 images, including 110 portraits

Available description: global (colour, texture, shape)

First page after 4 iterations



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[FCB04/1]

10



Illustrative example 2

Goal: find regions representing villages

Base of 24000 regions, 87 belong to the class

Available description: region features (colour, texture, shapes inside)

First page after 6 positive examples and 28 negative



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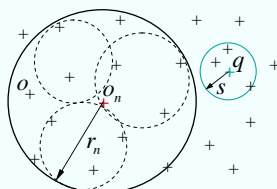
[FCB04/2]

11



Does relevance feedback scale?

- Two stages
 1. Learning: typically very few examples, can be fast if a fast learner is employed (e.g. SVM); still, is expensive with transductive learning!
 2. Selection of unlabeled sample the user should label: if all the unlabeled items in the database are evaluated, complexity $O(N)$!
- Many proposals for scaling retrieval by similarity (query by example), most of them fail when distance distribution is narrow
- An example: M-tree (metric search tree)



Subtree $N(o_n)$: objects o such that $d(o, o_n) \leq r_n$

Query q of range s

If $d(q, o_n) > r_n + s$ then the entire subtree $N(o_n)$ can be rejected (from triangular inequality)

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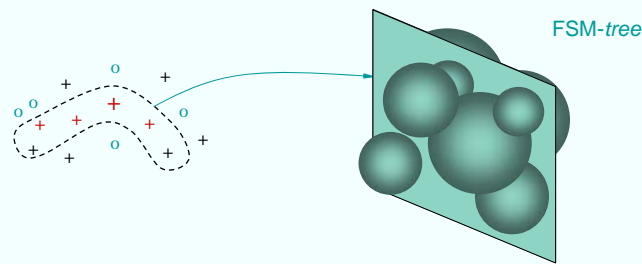
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12



FSM-tree and hyperplane queries

- What about relevance feedback?
- Principle of the method in [CEOT08]:
 - ◆ Classification with a 2-class SVM
 - ◆ Build an M-tree in the **feature** space of the kernel (FSM-tree)
 - ◆ Return the images that are closest to the **boundary**, found by a knn query in the FSM-tree with a **hyperplane**



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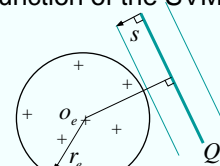
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13

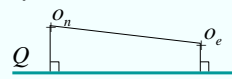
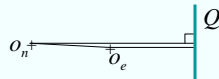
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FSM-tree and hyperplane queries

- Distance to the hyperplane:
$$d(Q, o_e) = \frac{|\sum_i \alpha_i y_i K(o_e, x_i) + b|}{\sqrt{\sum_{i,j} \alpha_i \alpha_j y_i y_j K(x_i, x_j)}}$$
- ($f(o_e) = \sum_i \alpha_i y_i K(o_e, x_i) + b$ being the decision function of the SVM)
- Pruning principle (test to reject a subtree):
 - ◆ If $d(Q, o_e) > r_e + s$ then the node is not retained for subsequent exploration



- How to avoid even more distance computations:



$d(Q, o_e) + d(o_e, o_n) \geq d(Q, o_n)$ but $d(Q, o_e) + d(Q, o_n) \not\geq d(o_e, o_n)$
 $\Rightarrow d(Q, o_e) \geq d(Q, o_n) - d(o_e, o_n)$ ($d(Q, o_e) \not\geq |d(Q, o_n) - d(o_e, o_n)|$), so
 if $d(Q, o_n) - d(o_e, o_n) > r_e + s$ then $d(Q, o_e) > r_e + s$



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RF with local features

- Application context: assisted plant species identification

- ◆ Relevant information only concerns a part of the image

- ◆ Additional difficulties:

- Strong background variations



- Scale and viewpoint variation



All plant images are provided by INRA

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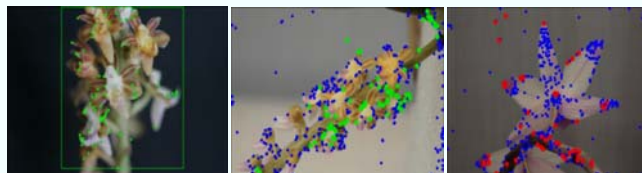
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15



RF with local features

- Use of local features (LF) with appropriate invariance and robustness characteristics
- User selects an image region to label as “relevant” or “irrelevant”
- Which part should the system consider in unlabeled images?
- Which unlabeled images should be considered? (all: too slow!)
- Add implicit feature selection to the user-provided selection



User target (left) and two candidate images with LF belonging to the target (green, middle) or not (red, right); the other LF (blue) are ignored

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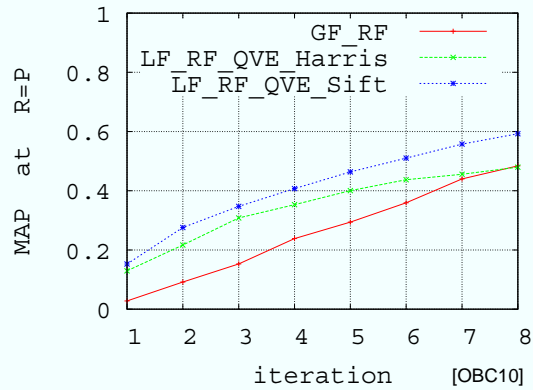
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16



Retrieval performance

- Comparison between two types of local features and global features (context can play a significant role for some databases...)



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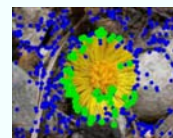
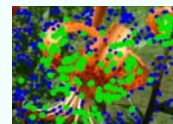
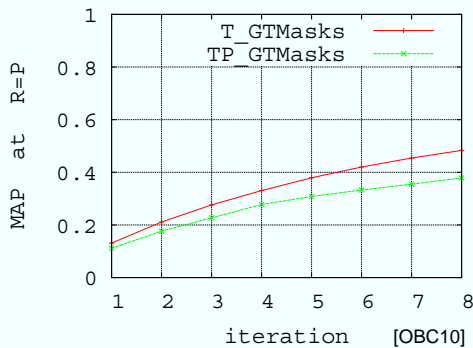
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17



Localization performance

- Implicit object localization (by LF similarity) is close to explicit localization (prior segmentation)



Images from Oxford Flower 17 database

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18



Scalable RF with local features

- Kernel approximation by hashing $k_h(\mathbf{x}, \mathbf{y}) \approx k(\mathbf{x}, \mathbf{y})$

$$k_h(\mathbf{x}, \mathbf{y}) = \langle \phi_h(\mathbf{x}), \phi_h(\mathbf{y}) \rangle \quad \phi_h(\mathbf{x}) = \underbrace{[0 \dots 0 \quad o_1 \quad 0 \dots 0 \quad \dots \quad 0 \dots 0 \quad o_n \quad 0 \dots 0]}^{\mathbb{R}^T}$$

$\underbrace{\hspace{10em}}_{\|Q\|} \quad \underbrace{\hspace{10em}}_{\|Q\|}$

$\underbrace{\hspace{5em}}_{h_1(\mathbf{x})=s} \quad \underbrace{\hspace{5em}}_{h_n(\mathbf{x})=t}$

- Hashing and active learning

$$f_h(\mathbf{x}) = \sum_{j=1}^s \alpha_j y_j k_h(\mathbf{x}, \mathbf{v}_j) - \beta$$

$$= \sum_{j=1}^s \alpha_j y_j \langle \phi_h(\mathbf{x}), \phi_h(\mathbf{v}_j) \rangle - \beta$$

$$= \left\langle \phi_h(\mathbf{x}), \sum_{j=1}^s \alpha_j y_j \phi_h(\mathbf{v}_j) \right\rangle - \beta$$



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Video mining by copy detection

- Goal: scalable content-based video copy detection for video stream surveillance and mining of large video databases
- “Copy” = **transformed** version of original content (photometric, geometric, temporal changes, post-production...)



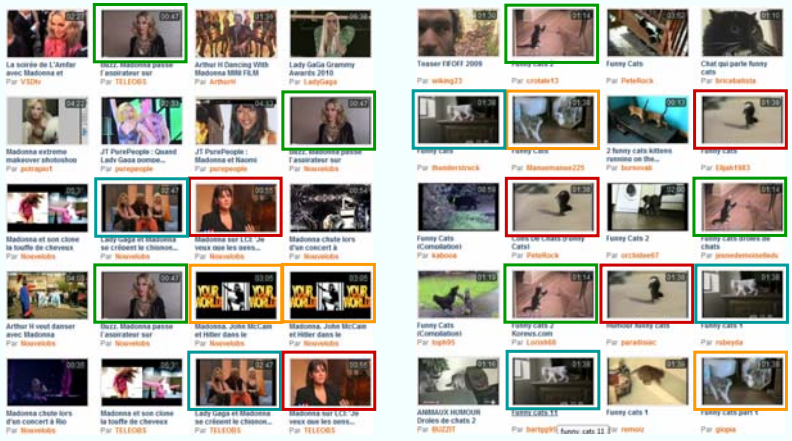
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Video mining by copy detection



Source: DailyMotion

Source: DailyMotion



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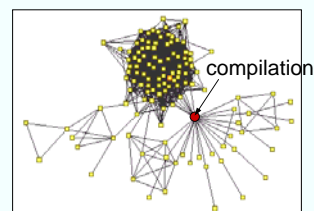
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21



Video mining by copy detection

- Large content archive (e.g. Institut National de l'Audiovisuel) context
 - ◆ Segmentation, labelling
 - ◆ Aided annotation
 - ◆ Media impact analysis
 - ◆ Media offer analysis
- Video sharing web site context
 - ◆ Cleanup (remove/reduce redundancy)
 - ◆ Organize: select representatives, identify characteristics
 - ◆ Mutualisation/filtering of keywords
 - ◆ New tools for navigation/visualisation



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22



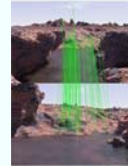
Description for copy detection

- Global description?
 - ◆ Not robust to expected transformations



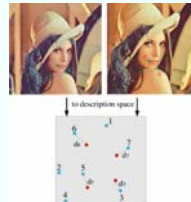
→ Local description

- ◆ SIFT, PCA-SIFT, GLOH, SURF?
 - Too robust to changes in scale, viewpoint...
 - Expensive (extraction, retrieval)



→ Improved Harris detector with differential descriptor

- Robust to changes in contrast, limited robustness to changes in scale
- Quite light (dimension = 20)



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Scalable mining by copy detection

- Preliminary work: stream surveillance
 - ◆ Z-grid, models of distortions and of the local density of signatures
 - Deferred real-time surveillance of one video stream against a database of 280 000 hours with 1 PC, detection rate ~95% for video fragments of more than 5 seconds
- Mining by copy detection = similarity self-join on the video database → complexity $O(N^2)$ (without an index)
- Alternative solutions:
 1. Direct use of the stream surveillance method (sequential reading the database, search of each keyframe in the database)
 2. Direct mining:
 - Similarity-based segmentation (redundant segments!) of the database
 - Similarity self-join within each segment



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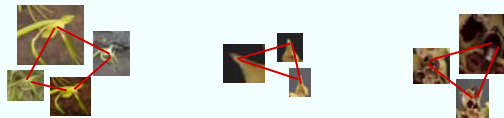
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Interactive retrieval after mining

- Complex concepts → very large search space
 - ◆ Learning: requires too much training data
 - ◆ Difficult to strongly reduce computational complexity of search
- Strong assumption: meaningful retrieval results rely on elementary regularities that can be found *a priori*
- Example for plant identification:
 - ◆ Identify complex patterns that are redundant in the database



- ◆ Can be done with methods related to copy detection!



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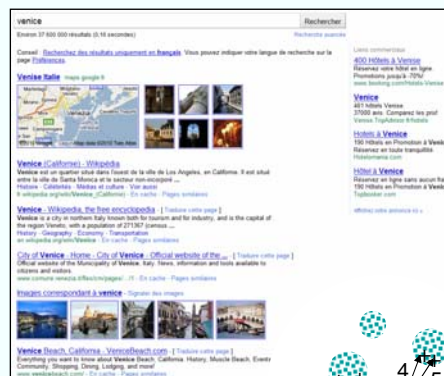
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27



IR beyond ranking

- What is **informative** in the results of search?
 - ◆ Potentially several meaningful views, each with a specific grouping
 - ◆ What about ranked answers?
 - ⇒ Mixture of many different dimensions of similarity
 - ⇒ Individual answers rather than relevant clusters
- ⇒ Ranking leads to a **loss** of information



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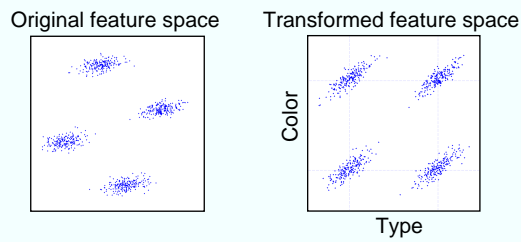
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28



Complementary clusterings [PC10]

- Complementary clusterings for a set of vectors, each clustering in a specific, arbitrarily oriented subspace
- Complementarity: one clustering provides little or no information regarding the other(s)



- Method: inspired by Tree-Component Analysis, but mutual information is computed between clusters in different subspaces



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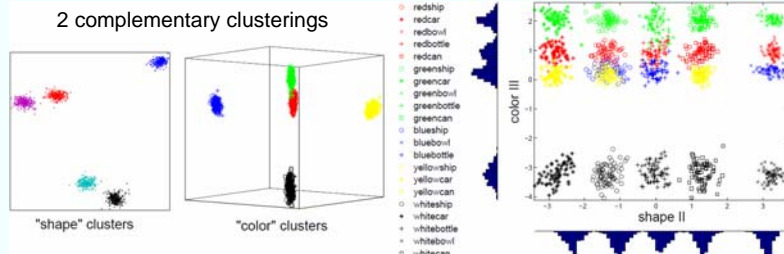
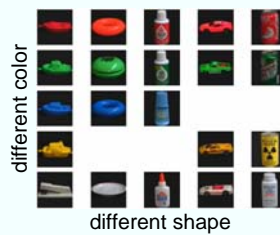
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Illustrative results

Data:
21 object classes,
72 viewpoints/class
Global descriptions



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[PC10]

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Conclusion

- Interactive retrieval/mining can allow to define/find task-dependent or user-dependent complex visual concepts/patterns
- Difficult but possible to scale such methods to large databases
- Search should provide more informative answers to user queries
- Prior mining allows to improve subsequent interactive retrieval (quality, speed, information content...)



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31

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32

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